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# Технический/Операционный мануал

Официальный дистрибьютор ООО «Русавтоматика» Санкт-Петербург, В.О., Малый пр-т 57, корп. 3, тел. (800) 600-33-47, www.rusavtomatika.com, e-mail: sales@rusavtomatika.com

2	<u> </u>		WARNING		
	W	NON-PROFESSIONALS THAT ARE NOT ALLOWED DEBUG, TEST AND REPAIR THE CONTROLLER.			
>			WARNING		
	< W	ENSURE	GOOD GROUNDING WHEN USING.		
	WARNING				
CONNECT	DISCONNECT ALL POWER BEFORE MAKING THE ELECTRICAL CONNECTION TO THE CONTROLLER WAIT 30 SECONDS BEFORE PROCEEDING TO THE NEXT STEP.				
	WARNING				
THIS CONTROLLER IS AN ELECTROSTATIC SENSITIVE EQUIPMENT, PAY ATTENTION TO TAKE ANTI-STATIC MEASURES IN USE AND MAINTENANCE.					
IFC RESERVES THE RIGHT TO MODIFY THIS MANUAL					

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#### Introduction

Congratulations on choosing our product.

This manual contains the technical specifications of the product, installation and wiring, functional operation and other aspects. In order to keep this product in the best working condition for a long time, please read this operation manual carefully before use, and keep it properly for reference at any time.

Due to the technical update, function enhancement and quality improvement of the product, there may be some differences between this operation manual and the actual product, please understand at that time.

No part of this manual may be reproduced or transmitted without the authorization of IFC.

The MES-150LC weight transmitter are high quality products specially designed for various industrial applications, using Delta-sigma analog-to-digital conversion and digital filtering processing technology. Through digital processing of the weak weight signal output by the load cell (group), output the corresponding analog signal to the user's upper system, through RS232/485 serial port communication, it is easy to form a weighing system with touch screen or PLC.

#### Order model:

Model	Functional Remarks	
MES-150LC	RS232, RS485 output, dual channel weight transfer	

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# 1. Safety Tips



#### • Do not use in hazardous environments

Avoid using this product in an environment with flammable gases and explosive dust. If you have this need, please choose our explosion-proof products.

#### • Avoid use in excessively hot environments

Avoid working in an overheated environment for optimal performance and service life.

Avoid direct sunlight on this product. When installing this product in a cabinet, install a cooling fan on the top of the cabinet.

#### • Weighing controller grounding protection

This product is a weak current equipment, and it should be isolated from strong current equipment when installed.

In order to prevent personal injury caused by electric shock accidents and to isolate this product from strong interference sources, be sure to connect the ground terminal of the weighing controller to the ground separately, and the ground resistance is required to be less than  $4\Omega$ .

#### • Cable laying

Weighing signals, analog signals and communication signal cables should be laid through pipes, and it is forbidden to lay them together with power cables.

#### • The weighing controller is powered

Before powering up, make sure that the input power supply voltage is correct.

#### • Environmental protection

Although this product is manufactured with lead-free components, there is a high risk of contamination after use in an industrial environment. Therefore,

when the whole machine is scrapped, please dispose of it legally as lead-containing industrial waste to avoid polluting the environment.

#### • Other matters

Personnel with appropriate professional knowledge and safe operation should be responsible for the installation, wiring and maintenance of this product. For safety matters not described in this operation manual, please follow the corresponding safety operation procedures and standards.

# 2. Standard Features

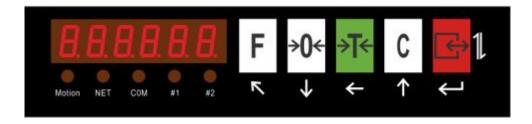
- 24VDC power input, the maximum power consumption is less than 6W.
- 2 load cell interface, support up to 6 \*350 ohm load cells
- Communication interface:

➢ 1 RS232 and 1 RS485 double serial port communication port, support Modbus RTU communication protocol.

- Multiple optional A/D weight update speed
- > Configure parameters and read results via Modbus-RTU
- Standard Industrial rail (DIN) mounting
- Temperature and humidity:
  - > Operating temperature :  $-10^{\circ}C \sim 50^{\circ}C$ , humidity :  $10\% \sim 95\%$ , non-condensing.
  - Storage temperature:  $-60^{\circ}C \sim 80^{\circ}C$ , humidity :  $10\% \sim 95\%$ , non-condensing.

# 3. Operation interface

# 3.1 Interface Diagram



# 3.2 Status indication & key operation

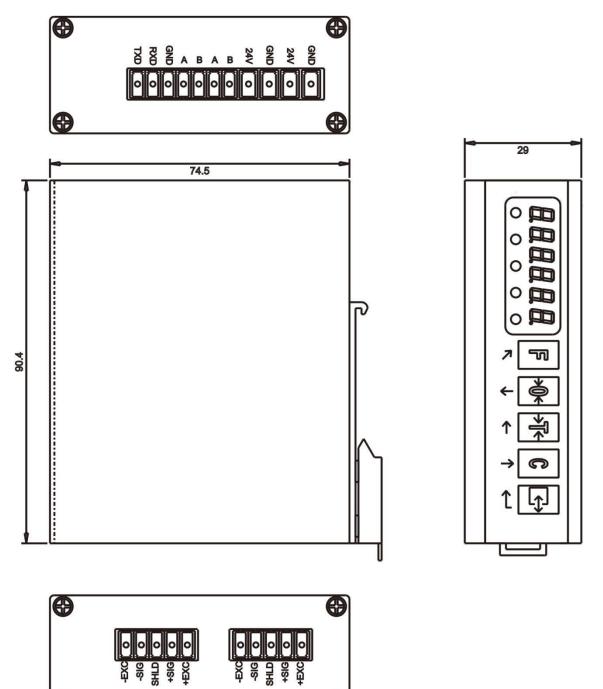
Indicator	Description
Motion	Motion (Light on when weighing is in motion)
NET	Net weight (Light on when weight is net)
СОМ	Communication light (the light flashes while communicating)
# 1	Display channel 1
# 2	Display channel 2

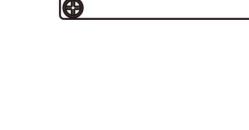
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Keys	Description
	Setup mode: ESC(Exit) menu
r,	Weighing mode: Node address can be viewed
<b>→</b> 0 <del>&lt;</del>	Weighing mode: Zero
<b>≯</b> ]€ ←	Weighing mode: Tare Setup mode: Left switch
C	Weighing mode: Clear
1	Setup mode: Up switch / increase digit
¢	Setup mode: Confirm
÷	Change channel
<b>₽ ₽</b>	Press ⊾ first, then press ← to enter
	the menu
	Long press to enter the Quick
	Calibration Menu
F	CH1 C0: Scale 1 zero point calibration
<b>N</b>	CH1 LD: Scale 1 capacity calibration
``	CH2 CO: Scale 2 zero point calibration
	CH2 LD: Scale 2 capacity calibration

# 4. Installation/interface/wiring

### 4.1 Installation





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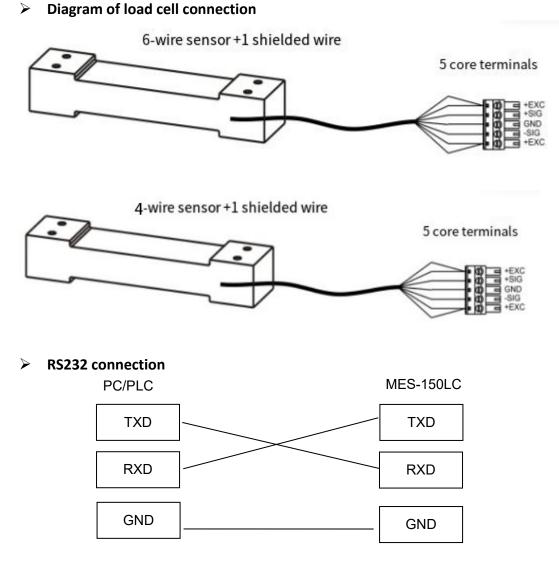
# 4.2 Interface

Load cell interface(2 channels)					
Diagram of terminal	Serial number	Pins	Description		
	1	+EXC	Positive excitation terminal		
EXC EXC EXC EXC EXC EXC EXC EXC	2	+SIG	Positive signal terminal		
The picture shows a 4-wire sensor, if a	3	SHLD	Shielded ground terminal		
6-wire sensor is used, it is require to short-circuit+EXC and +SEN to +EXC, and	4	-SIG	Negative signal terminal		
short-circuit -SEN and -EXC to -EXC.	5	-EXC	Negative excitation terminal		
Pow	er interfac	e			
Diagram of terminal	Serial number	Pins	Description		
	1	+24V (power positive)	DC power supply positive		
GND 24V 24V	2	GND (Power negative)	DC power supply negative		
Use 2 sets of 2-core terminals	3	+24V (power positive)	DC power supply positive (junction combined)		
	4	GND (power supply negative)	Dc power supply negative (junction connected)		
Commun	ication into	erface			
Diagram of terminal	Serial number	Pins	Description		
TXD SQ A B A B	1	TXD	COM1 RS232 Sending end		
Supports standard RS232 and RS485, and	2	RXD	COM1 RS232 Receiving end		
can configure communication parameters	3	GND	RS232/RS485GND		
independently. Note: RS485 requires grounding to increase	4	RS485A	COM2 RS485 +		



communication interference.	5	RS485B	COM2 RS485 -
	6	RS485A	COM2 RS485 (junction combined)
	7	RS485B	COM2 RS485 (junction combined)

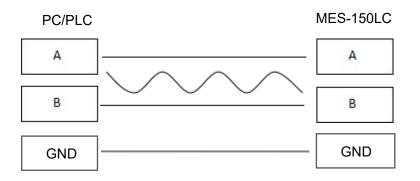
### 4.3 Wiring



RS232 transmission distance does not exceed 15 meters



#### RS485 connection



RS485 transmission distance does not exceed 600 meters.

# 5. Parameter setting

### 5.1 Metrology calibration menu

#### > F1 Channel 1 calibration

First-level menu	Second-level menu				
Prompt	Prompt	Factory setting	Setting	Description	
	(F I. I) Minimum Division	0. 1	0.000 I ~ 50	0.000 I, 0.0002, 0.0005, 0.00 I, 0.002, 0.005, 0.0 I, 0.02, 0.05, 0. I, 0.2, 0.5, 1,2, 5, 10, 20, 5 0	
FI	(F 1.2) Capacity	3000	0~ 80000 0	Set the capacity of the scale	
Channel 1 calibration	(F 1.3) Calibration mode	0	0~2	<ul><li><i>G</i>: Weight calibration</li><li><i>I</i>-Weight-free calibration</li><li><i>2</i>: Three-point calibration</li></ul>	
	(F I.Y) Calibration Zero calibration process			Clear the weighing platform, do the zero calibration	
	<pre>{F 1.5} Three-point calibration-second point calibration</pre>	Calibration process		The second point of the three-point calibration	



Сар	(F 1.6) pacity calibration	Calibration process	Enter the current weight of the weighing platform and do weight calibration
	(ד.ו ۲		
Loa	ad cell sensitivity		
	(F 1.8)		
Lo	oad cell capacity		

#### **Calibration operating instructions:**

This menu can set the minimum division,full scale,zero point calibration of the instrument.

#### > (F I. I) Minimum Division

Press $\leftarrow$ and $\overset{\frown}{\overset{\frown}{}}$ enter (F 1), press $\xleftarrow{\leftarrow}{}$ enter (F 1.1), press $\xleftarrow{\leftarrow}{}$ enter minimum division
edit mode.Press ↑ or ↓ select division.Press ← save data and enter (F 1.2),press ⊾ exit.
> (F I.2) Capacity
G       >⊙         Select {F !.2}.press ← enter capacity edit mode.Press ↑ or ↓ select capacity range.Press ←
save data and enter (F 1.3), press exit.
> (F 1.3) Calibration mode
Select (F 1.3), press $\leftarrow$ enter calibration mode selection, press $\uparrow$ or $\downarrow$ select calibration

mode.

#### The selection of calibration mode is shown in the following figure:

Calibration mode	Parameter setting	Description
0- Weight calibration	(F 1.3)	Select (F 1.3), press $\leftarrow$ enter calibration mode selection. Press $\uparrow$ or $\downarrow$ select calibration mode. Press $\leftarrow$ save data and enter (F 1.4), press $\checkmark$ exit.

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	(F I.4)	Select (F 1.4), press $\leftarrow$ to display [RL 0], clean the weighing platform, press $\leftarrow$ , after 10 seconds countdown. [RL 0+ is displayed. Press $\leftarrow$ save data and enter (F 1.5), press $\sim$ exit.
	(F 1.6)	Select (F 1.6), press $\leftarrow$ enter capacity calibration edit mode, press $\uparrow$ or $\downarrow$ select capacity range and load corresponding weights. For example200, enter the 200 on terminal and then load 200g weights on weighing platform, press $\leftarrow$ start capacity calibration, after 10 seconds countdown, <i>CRL 0</i> is displayed. Press $\leftarrow$ Save data.
	(F 1.3)	Same like weight calibration (F 1.3)
/- Weight Free	(F I.7)	Select (F 1.7), press $\leftarrow$ enter (F 1.7), press $\uparrow$ or $\checkmark$ adjust sensor sensitivity(see sensor manual for sensor sensitivity).Press $\leftarrow$ save data and enter (F 1.8).Press $\backsim$ exit.
calibration	(F 1.8)	Select ( <i>F</i> 1.8), press $\leftarrow$ enter ( <i>F</i> 1.8), press $\uparrow$ or $\downarrow$ enter sensor capacity (see sensor manual for sensor capacity). Press $\leftarrow$ save data and enter ( <i>F</i> 1.8). Press $\bigtriangledown$ exit.

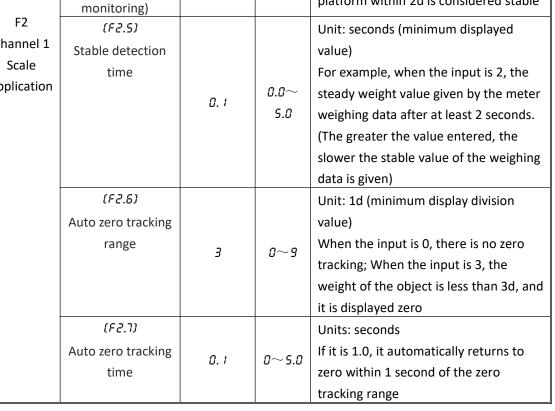
Press  $\begin{bmatrix} F \\ -\infty \end{bmatrix}$  exit menu, and then load the corresponding weights on the meter, if the output value of the meter is larger than the actual value, you need increase the sensitivity of the sensor; If the output value of the meter is smaller than the actual value, the sensitivity of the sensor needs to be reduced accordingly.

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## 5.2 Weighing application menu

#### **First-level** Second-level menu menu Factory Prompt Setting Description Prompt setting (F2.1) 0: Low speed 1: medium speed 2 0~3 2: High speed 3: Highest speed Rate (F2.2) 4 : heaviest 0 : lightest The larger the value, the stronger the Filter 0~Y l anti-interference, but the reading is slow, which needs to be set according to the actual situation on site (F2.3) Press the ZERO key to reset the meter 0~99 99 to zero. Auto zero range Percentage of capacity ( $F \downarrow .2$ ) (F2.4)Unit: 1d Stable detection d is the minimum division (F 1. 1) 0~99 20 range If the value is 2, the change of the scale (Dynamic platform within 2d is considered stable monitoring) F2 (F2.S) Channel 1 Stable detection value) Scale time application 0.0 $\sim$ 0.1 5.0 data is given)

#### > F2 Channel 1 Scale application





(F2.8) Weight units	2	0~3	0:None 1:g 2:kg 3:t
(F2.9) Motion clear and tare	1	/ or []	1: Allowed 0: Forbidden
(F2.10) Tare with negative gross weight	1	I or D	1: Allowed 0 : Forbidden Whether to accept tare when the gross weight of the instrument is less than zero.
(F2. I I) Over capacity	0	0-99	Unit: 1d (minimum display value) Upper overload detection range beyond full scale
( <i>F2. 12)</i> Under zero	0	0-99	Unit: 1d (minimum display value) Lower overload detection range beyond zero.

# 5.3 Communication Interface menu

#### > F6 Communication interface

First-level menu		5	Second-leve	el menu	
Prompt	Prompt	Factory setting	Setting	Description	
	(F5. 1) COM1	2-FEU	2~0	0: None 1: Continuous output 2: Modbus - RTU (division)	
	(F6.2) COM1 continuous output mode	2-[ 2-5	I~2	<ol> <li>Continuous output format 1 (no check)</li> <li>See appendix for output format</li> <li>Continuous output format 2 (with check)</li> <li>See appendix for output format</li> </ol>	
	(F6.3) COM1 Modbus address	1	0~255	Modbus-Rtu node address This change requires a reboot	
F6 Communic ation interface	(F5.4) COM1 Baud rate	38400	1200 ~ 57600	Unit: bit/s 1200、2400、4800、9600、 19200、 38400、 57600、 1 15200	
interface	(F&.5) COM1 Data format	2	0~5	D7E I:7 data bits, 1 stop bits, even checkI7D I:7 data bits, 1 stop bit, odd check2BII I:8 data bits, 1 stop bit, no check3BI2:8 data bits, 2 stop bits, no checkYBE I:8 data bits, 1 stop bit, even check5BD I:8 data bits, 1 stop bit, odd check	
	(F6.6) COM1 Continuous output frequency	Б	0~ IOO	If it is 0, do not send	





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(F5.7) COM2	2-5-60	0~2	0: None 1: Continuous output 2: Modbus - RTU (division)
(F6.8)	2-06-9	ı~2	1: Continuous output format 1 (no check) See appendix for output format
COM2 Continuous Output mode			2: Continuous output format 2 (with check) See appendix for output format
(F5.9) COM2 Modbus address	I	0~255	Modbus-Rtu node address This change requires a reboot
		1200	Unit: bit/s
(F6. 10)	38400	$\sim$	1200、2400、4800、9600、19200、
COM2 Baud rate		57600	38400、57600、115200
	2	0~5	D7E I:       7 data bits, 1 stop bits, even check         I7D I:       7 data bits, 1 stop bit, odd check
(F5. 1 1) COM2			2801: 8 data bits, 1 stop bit, no check
Data format			3802: 8 data bits, 2 stop bits, no check
			<i>YBE I</i> : 8 data bits, 1 stop bit, even check
			580 /: 8 data bits, 1 stop bit, odd check
(F5. 12) COM2 Continuous output frequency	6	0~50	If it is 0, do not send
output frequency			

Standard support RS232 and RS485 independent can work at the same time serial port communication, COM1 for RS232, COM2 for RS485, both support continuous output, Modbus - RTU and command mode.

Modbus - RTU must select 8 data bits

# 5.4 Maintaining the test menu

### > F10 Restore default values

First-level menu	Second-level menu		
Prompt Prompt Description		Description	
F10	(F 10. 1)	Restore default values	
Restore default (F 10.2)		Restore default values	
values	(F 10.3)	Restore default values	

#### > F11 System Information

First-level menu	Second-level menu						
Prompt	Prompt	Description					
	(F   I, I)	Display the companying value for shorted 1.4 /D					
	AD inner code	Display the conversion value for channel 1 A/D					
	(F   I.2)						
	AD inner code	Display the conversion value for channel 2 A/D					
	(F   I.S)	Displays program version information					
F11	Display program version	such as UFD 1.05					
System Information	(F 11.5) Test serial output	Terminal displays 5nd 123 (default) ,press confirm and terminal sends 123 to device connected to serial port of terminal					
	(F + I.7) Test channel 1 load cell signal	Display the millivolt value of the load cell signal					
	(F 11.8) Test Channel 2 load cell signal	Display the millivolt value of the load cell signal					



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## **Appendix A Modbus**

Modbus is a network communication protocol in the form of master and slave. The instrument is called by the upper system as a slave in Modbus network.

Data format is RTU mode, support "03" and "06" function code.

To use Modbus communication protocol, "Communication mode" under the menu of "Communication parameters" should be set to Modbus.

This instrument is written according to the standard Modbus protocol of Modicon company. The bits of each byte or character are as follows:

Address	Position	Description
40001	L	1 cools surrout not usight (displayinglus) (22 hit signed integer)
40002	Н	1 scale current net weight (display value) (32-bit signed integer)
40003	L	2 ccale current not weight (display yalva) (22 hit signed integer)
40004	Н	2 scale current net weight (display value) (32-bit signed integer)
	Bit0	Reserved
	Bit1	Reserved
	Bit2	Reserved
	Bit3	Reserved
	Bit4	Reserved
40005	Bit5	Reserved
1 scale	Bit6	Reserved
terminal status	Bit7	Reserved
	Bit8~Bit9	Decimal place: 0=0 decimal places; 1=1 decimal place; 2=2 decimal places; 3=3 decimal places
	Bit10~Bit12	Reserved
	Bit13	Motion
	Bit14~Bit15	Reserved
40006		Reserved
	Bit0	Reserved
	Bit1	Reserved
	Bit2	Reserved
	Bit3	Reserved
10007	Bit4	Reserved
40007	Bit5	Reserved
2 scale terminal status	Bit6	Reserved
	Bit7	Reserved
	Bit8~Bit9	Decimal place: 0=0 decimal places; 1=1 decimal place; 2=2 decimal places; 3=3 decimal places
	Bit10~Bit12	Reserved
	Bit13	Motion

#### Read only address description



	Bit14~Bit15	Reserve
40518-40519		The weight value calibrated on the scale 1, is a 32-bit signed integer.
40520-40521		The weight value calibrated on the scale 2, is a 32-bit signed integer.

#### > Read only address description

Read only address return 0 when receiving the read command.

Address	Position	Description				
		Scale	1			
	Bit0	1 = Zero	The priority judgment level of bit0 to bit 2			
40511	Bit1	1 = Tare	is progressively reduced.			
1 scale	Bit2	1 = Clear	It is only available when production is			
Control			stopped			
	Bit3~15		Reserved			
40512			1= Zero calibration			
40513		Weight value of calibration. It is a 16-bit signed integer.				
40514		Reserved				
		Scale	2			
	Bit0	1 = Zero	The priority judgment level of bit0 to bit2			
40515	Bit1	1 = Tare	is progressively reduced.			
2 scale	0.1.2		It is only available when production is			
Control	Bit2	1 = Clear	stopped			
	Bit3~15		Reserved			
40516			1= Zero calibration			
40517		Weight value	of calibration. It is a 16-bit signed integer.			
		The weight value calibrated on the scale 1, is a 32-bit signed				
40518-40519			integer.			
40500 40504		The weight valu	e calibrated on the scale 2, is a 32-bit signed			
40520-40521		integer.				



# Appendix B Continuous output format

Continuous Output (1) (no checksum)

Data	S T X	S W A	S W B	S W C	хххххх	хххххх	C R
Note	Α	В	С	D	E	F	G

#### Continuous output (2) (Checksum)

Data	S T X	S W A	S W B	S W C	хххххх	хххххх	C R	С Н К
Note	Α	В	С	D	E	F	G	н

#### Interpretation of each data item:

- A -- STX: ASCII 02H
- B -- SWA: Status Byte A
- C SWB: Status Byte B
- D SWC: Status Byte C
- E Net weight, 6 digits, no decimal point included
- F Gross weight, 6digits, no decimal point included
- G -- CR: ASCII 0DH
- H CHK: checksum Checksum

CHK plus the lower 7 bits of the other data in each row add up to 0

	SWA: Status Byte A							
Bit								
		Bit2	Bit1	Bit0	Weight Decimal Position			
		0	0	1	XXXXX0			
0		0	1	0	XXXXXX			
1		0	1	1	XXXXX.X			
2		1	0	0	XXXX.XX			
		1	0	1	XXX.XXX			
		1	1	0	XX.XXXX			
3 4		Bit4	Bit3		Increment Size Factor			
4		0	1		X1			
		1	0		X2			
		1	1		X5			
5					Always 1			
6		Always 0						
7					Always 0			

	SWB: Status Byte B						
Bit							
0	0 - Gross weight, 1 - Net weight						
1	0 - Positive weight 1 - Negative weight						
2	1 - Under zero or over capacity						
3	1 - Motion						
4	Always 0						
5	Always 1						
6	0 - Normal operating status, 1 - The meter is being powered on and initialized						
7	Always 0						

SWC: Status Byte C	
Bit	
0	Always 0
1	Always 0
2	Always 0
3	Always 0
4	Always 0
5	Always 1
6	Always 0
7	Always 0

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